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Equilibrium of a Rigid Body in Two Dimensions 4 - 10 • For known forces and moments that act on a two-dimensional structure, the following are true: $F_z = 0$ $M_x = M_y = 0$ $M_z = M_O$ • Equations of equilibrium become $\sum F_x = 0$ $\sum F_y = 0$ $\sum M_A = 0$ where A can be any point in the plane of the body.

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Edition. 4 - 15. Equilibrium of a Two-Force Body • Consider a plate subjected to two forces F_1 and F_2 • For static equilibrium, the sum of moments about A must be zero. The moment of F_2 must be zero. It follows that the line of action of F_2 must pass through A • Similarly, the line of action of F_1 must pass

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• Differential vector is the dr particle displacement. r • Work of the force is $F dx + F dy + F dz + F ds = dU = F dr = x + y + z = =$ • $\cos \alpha$ r • Work is a scalar quantity, i.e., it has magnitude and sign but not direction. • Dimensions of work are Units are length \times force. $1 \text{ J (joule)} = (1 \text{ N})(1 \text{ m})$
 $1 \text{ ft} \cdot \text{lb} = 1.356 \text{ J}$

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TO THE INSTRUCTOR As indicated in its preface, Vector Mechanics for Engineers: Statics is designed for the first course in statics offered in the sophomore year of college. New concepts have, therefore, been presented in simple terms and every step has been explained in detail.

(Solution Manual) Ferdinand P. Beer, E. Russell Johnston ...

Vector Mechanics for Engineers: Statics. This text helps to develop a student's ability first to analyze problems in a simple and logical manner, and then to apply basic principles to their solutions. A strong conceptual understanding of these basic mechanics principles is essential for successfully solving mechanics problems.

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Edition Eighth Vector Mechanics for Engineers: Dynamics Sample Problem 15.8 • The angular accelerations are determined by simultaneously solving

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the component equations for $\mathbf{r}_D = \alpha \mathbf{DE} \times \mathbf{r}_D - \omega \mathbf{DE} \times \mathbf{r}_D - (11.29) (-17\mathbf{i} + 17\mathbf{j}) \times \mathbf{r}_D = -17\alpha \mathbf{DE} \mathbf{i} - 17\alpha \mathbf{DE} \mathbf{j} + 2170\mathbf{i} - 2170\mathbf{j}$
 $\mathbf{r}_B = \alpha \mathbf{AB} \times \mathbf{r}_B - \omega \mathbf{AB} \times \mathbf{r}_B = 0 - (20) (8\mathbf{i} + 14\mathbf{j}) \times \mathbf{r}_B = -3200\mathbf{i} + 5600\mathbf{j}$
 $\mathbf{r}_D = \alpha \mathbf{BD} \times \mathbf{r}_D \dots$

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